

## **A Composite Estimator for the Total in a Finite Population**

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**Abstract.** We consider the situation in which the sampled population is a subset of a larger finite population that is “exposed to sampling” according to a certain probability distribution. The exposure probabilities are determined independently of the sampling method used. A composite estimator is proposed for the population total together with approximate formulae for its expectation and variance. An unbiased estimator for the approximate variance is also suggested.

### **1. Introduction**

It sometimes happens that the actually sampled population is itself a subset of a finite target population that gets ‘exposed’ to sampling according to some probability distribution. The probability distribution is independent of the sampling method used, and the sampler has no means for controlling it. For example, in sampling the population of a town, we may decide, for convenience, to take the sample from among those individuals who attended an outpatient clinic such as E.N.T. or Eye clinic. The group of individuals attending the clinic at a specified period of time may be looked at as a subgroup of the inhabitants of the town that is exposed to the clinic in accordance with a chance mechanism. And although it is possible, through a properly chosen sampling procedure, to control the selection probabilities, it is not possible to do the same for exposure probabilities of units in the target population. As a result, if a target population parameter is to be estimated, we can not rely solely on a design-based estimator since a model specifying the manner in which units in the actual population are generated from the target population has to be set. A sort of model-design-based estimator must therefore be resorted to.

The main problem with modelling in the analysis of surveys stems from the fact that it is usually difficult, in practice, to estimate bias in the estimator or detect departures from the model [1]. Attempts for combining model-based and design-based estimators into a composite estimator were made in the field of small area estimation, by Schaible [2] and Fay and Herriot [3]. In this paper an estimator, based partly on a model and partly on design, is suggested for the population total. We shall call it composite because of its mixed nature although this term is usually used for an estimator that represents a combination of two separate estimators.

## 2. The Problem

We have a finite target population  $U$  of  $N$  units. A sample of size  $n$  is to be taken from  $U$  by some method. The sampler, however, cannot sample  $U$  itself but can only sample a subset of it,  $S_k$  say, of size  $k$ , that happened to be exposed to sampling. The value of  $k$  is fixed in advance and satisfies  $n < k < N$ . The exposed subset  $S_k$  is a random realization following the conditional (on  $k$ ) distribution  $P(S_k)$ .

Our problem is to estimate the total  $T$  of a characteristic  $y$  in the population  $U$ . Of course if the sample size is not fixed, the exposed subset which we may then denote by  $S$  will follow the unconditional distribution  $P(S)$ , and the size of  $S$ ,  $K$  say, will be a random variable satisfying  $0 \leq K \leq N$ . In the example of the outpatients clinic, individuals in the town form  $U$ , those in the clinic  $S_k$ , while fixing  $K$  at  $k$  will mean sampling only subsets of  $U$  of size  $k$ .

## 3. Exposure Probability and Inclusion Probability

Let  $I_i$  be an exposure indicator taking the value 1 if unit  $i$  is exposed but 0 otherwise. The exposure probability of unit  $i$ ,  $p_i$  say, is

$$p_i = \text{prob}(I_i = 1) = E(I_i) \quad i = 1, \dots, N$$

while the conditional exposure probability for unit  $i$ , given that the number exposed is fixed at  $k$ , is

$$p'_i = \text{prob}(I_i = 1/K = k) = E(I_i = 1/K = k) \quad i = 1, \dots, N$$

Similarly, the conditional exposure probability for units  $i$  and  $j$  is

$$p'_{ij} = \text{prob}(I_i I_j = 1/K = k) \quad i = 1, \dots, N$$

The  $p'_i$  and  $p'_{ij}$  can be expressed in terms of the  $p_i$ . For if we let

$$\sum_i^N p_i = N^*, \quad d = \sum_i^N p_i$$

$(1 - p_i)$ , then it can be shown (Hájek [4] pp. 83 and 142) that

$$p'_i = p_i \left[ 1 + \frac{(k - N^*)(1 - p_i)}{d} + \frac{(k - N^*)^2 - d}{d^2} x (1 - p_i)(\bar{p} - p_i) + o(d^{-1}) \right]$$

...  $1 \leq i \leq N$  ... (3.1)

Where  $\bar{p} = \sum_i^N p_i^2 (1 - p_i) / d$ , and where  $o(d^{-1})d \rightarrow 0$  as  $d \rightarrow \infty$  provided that  $|k - N^*|d^{\frac{1}{2}}$  remains bounded by a constant independent of  $d$ . Also,

$$p'_{ij} = p_i p_j \left[ 1 + \frac{2 - p_i - p_j}{d} (k - N^*) + \frac{(k - N^*)^2 - d}{d^2} \right. \\ \left. \left[ (1 - p_i)(\bar{p} - p_i) + (1 - p_j)(\bar{p} - p_j) + (1 - p_i)(1 - p_j) \right] + o(d^{-1}) \right]$$

...  $1 \leq i \neq j \leq N$  ... (3.2)

where  $d o(d^{-1}) \rightarrow 0$  in probability.

Now if we assumed that:

$$p_i = p \quad \text{all } i \dots \quad \dots (3.3)$$

then since  $\sum_i^N p_i = N^*$ , it follows that  $p = N^* / N$  so that on using (3.1) and (3.2) we have the asymptotically valid results:

$$p_i = p'_1 \sim \frac{k}{N} \quad \text{all } i \quad \dots (3.4)$$

$$p'_{ij} = p'_2 \sim \frac{k^2 - N^* + N^{*2} / N}{N^2} \quad \text{for all } i \ \& \ j \ (i \neq j) \quad (3.5)$$

Suppose a sample of  $n$  units is to be drawn from  $S_k$ . Denote by  $\pi_i(k)$  the overall inclusion (in the sample) probability for unit  $i$  given that  $k$  units are exposed, and by  $\pi_{ij}(k)$  the overall inclusion probability, given  $k$ , for units  $i$  and  $j$  ( $i \neq j$ ). Define the inclusion

indicator  $t_i$  that takes the value 1 or 0 depending on whether or not unit  $i$  ( $i = 1, \dots, N$ ) is included in the sample. It follows that:

$$\begin{aligned} \pi_i(k) &= \text{Prob. } (t_i = 1/K = k) \\ &= \text{Prob. } (i \text{ exposed and selected } / K = k) \\ &= \text{Prob. } (i \text{ selected} / i \text{ exposed and } K = k) \text{ Prob. } (i \text{ exposed} / K = k) \end{aligned}$$

Assuming (3.3) and using (3.4), we have

$$\pi_i(k) = m_i p_1' \quad \dots (3.6)$$

where  $m_i = \text{Prob } (i \text{ selected } / i \text{ exposed and } K = k)$ . By a similar argument:

$$\pi_{ij}(k) = m_{ij} p_2' \quad \dots (3.7)$$

where  $m_{ij}$  is the probability that both  $i$  and  $j$  ( $i \neq j$ ) are selected given that they are both exposed and  $K = k$ . The inclusion probabilities (3.6) and (3.7), each consists of two factors: One factor ( $p_1'$  and  $p_2'$ ) is determined independently of the sampling method used and can not be controlled. The other factor ( $m_i$  or  $m_{ij}$ ) is dependent on the sampling method, and can thus be controlled by the sampler. For example the units can be selected so that the  $m_i$  are proportional to a measure of size.

Finally to obtain the explicit forms of  $P(S)$  and  $P(S_k)$  we note that if  $p_1, p_2, \dots, p_N$  is any sequence of numbers, here exposure probabilities, satisfying  $0 \leq p_i \leq 1$  for all  $i$  and if  $S$  is an arbitrary subset of  $U$  and  $r$  its complement in  $U$ , then assuming the  $I_i$  independent

$$P_{(S)} = \prod_{i \in S} p_i \prod_{i \in r} (1 - p_i) \quad \dots (3.8)$$

If the number exposed is fixed at  $k$ , we have

$$\begin{aligned} P_{(t_k)} &= C^* \prod_{i \in S} p_i \prod_{i \in r} (1 - p_i) \quad \text{if } K = k \\ &= 0 \quad \text{if } K \neq k \end{aligned} \quad \dots (3.9)$$

with  $C^* = C^*(p_1, \dots, p_N)$ , where  $C^*$  is such that  $\sum^c P(S_k) = 1$  and the summation is over all  $C = \binom{N}{k}$  distinct subsets of size  $k$ . In the terminology of Hájek [4] (3.8) and (3.9) define Poisson sampling and rejective sampling respectively.

As a result if we assume that the number exposed is fixed at  $k$  and that  $p_i = p$  for all  $i$ , the non zero value in (3.9) becomes

$$C^* p^k (1 - p)^{N-k}$$

Summing this over all subsets of size  $k$  and equating to 1 we have

$$C^* = \frac{1}{C p^k (1-p)^{N-k}}$$

so that

$$p(s_k) = \frac{1}{C} \dots (3.10)$$

if  $K = k$  but equals 0 otherwise.

#### 4. Estimation of the Population Total

In this section we estimate the total  $T$  of characteristic  $y$  in  $U$  on the basis of a sample of size  $n$  from the exposed subset  $S_k$ . We assume that exposures are independent and that the total number of units exposed is fixed at  $k$ . Furthermore, we make the simplifying assumption that the conditional exposure probabilities  $p'_i$  and  $p'_{ij}$  of a unit and of two different units respectively, are as given by (3.4) and (3.5), and that the conditional distribution of  $S_k$  is given by (3.10).

Define the subclass of linear estimators

$$\hat{T}_1^* = \sum_i^n \beta_i y_i \dots (4.1)$$

where the  $\beta_i (i = 1, \dots, N)$  are constants. For  $\hat{T}_1^*$  to be unbiased given  $K = k$ , we must have

$$E\left(\hat{T}_1^* / k\right) = \sum_i^N \pi_i(k) \beta_i y_i = \sum_i^N y_i = T \dots (4.2)$$

or, in view of (3.6),

$$\sum_i^N m_i p'_i \beta_i y_i = T$$

This requires that

$$m_i p'_i \beta_i = 1 \quad i = 1, \dots, N$$

so that

$$\hat{T}^* = \sum_i^n \frac{y_i}{p'_1 m_i} = \sum_i^n \frac{y_i}{\pi_i(k)} \quad \dots (4.3)$$

is an unbiased estimator of  $T$ . It is the only unbiased estimator in the subclass (4.1) and is thus the 'best' estimator in that subclass. Note however that the expectation in (4.2) is conditional since averaging is made over all subsets of size  $k$ . The estimator  $\hat{T}^*$  will have zero variance if

$$\pi_i(k) = \frac{ny_i}{T}$$

*i.e* if the  $\pi_i(k)$  are proportional to the  $y_i$ . Let  $x$  be a characteristic the value of which is positive and known for all units in the population. If  $x_i$ , the value of  $x$  for unit  $i$ , is approximately proportional to the  $y_i$ , we may expect considerable reduction in the variance of  $\hat{T}^*$  if the  $\pi_i(k)$  are made proportional to the  $x_i$ . If for example we managed to make

$$\pi_i(k) = \frac{nx_i}{\sum_i^N x_i}$$

and if  $x$  and  $y$  are strictly proportional, (*e.g.* Cochran [5], p. 259)  $x_i / \sum_i^N x_i$  will equal  $y_i / T$  and  $\hat{T}^* = T$  which has zero variance.

The characteristic  $x$  can be any variable positively correlated with  $y$  provided that its values are positive and known for all units in  $U$ . It may, for example, be a measure of size, an eye estimate of  $y$ , or the value of  $y$  at a previous occasion. It may also be a characteristic known to be positively correlated with the phenomenon under study such as age.

Now, if  $k = N$ , then  $S_k = U$  and  $p'_1 = 1$ . The estimator  $\hat{T}^*$  is then the usual Horvitz - Thompson estimator  $\hat{T}_{HT} = \sum_i^n y_i / m_i$ . For this estimator, several methods are available for satisfying the condition  $m_i = nx_i / \sum_i^N x_i$  when sampling without replacement.

Among these are the methods of Durbin [6], Sampford [7], Samiuddin and Asad [8], Chao [9], Chakrabarti [10], Gupta *et al.* [11], Lahiri [12], and Midzuno [13]. When, however,  $k < N$  as is here assumed,  $\pi_i(k)$  contains the factor  $p'_1$  which is uncontrollable. On the other hand the sampler is sampling  $S_k$  rather than  $U$  itself. By a suitable method of selection we may achieve

$$m_i = \frac{nx_i}{\sum_i x_i} \quad \dots (4.4)$$

but then  $\hat{T}^*$  will not equal  $T$  even under strict proportionality between  $x$  and  $y$ , and hence no reduction in variance may be gained. Let us set

$$X = \sum_{i=1}^N x_i, \quad X_k = \sum_{i=1}^N x_i$$

and put

$$X_k = \alpha X \quad \dots (4.5)$$

Using (3.6), (4.4) and (4.5) we have

$$\pi_i(k) = \frac{nx_i p'_1}{\alpha X} \quad \dots (4.6)$$

so that, in view of (4.6) and (4.3) and assuming strict proportionality between  $x$  and  $y$  we get:

$$\hat{T}^* = \frac{\alpha}{p'_1} T$$

Hence, if we require an estimator with zero variance under strict proportionality, we may take

$$\hat{T} = \frac{p'_1}{\alpha} \sum_i \frac{y_i}{m_i p'_1} = \frac{1}{\alpha} \sum_i \frac{y_i}{m_i} \quad \dots (4.7)$$

<sup>11</sup> If  $x$  and  $y$  are strictly proportional, and the sample is selected such that (4.4) is satisfied,  $\hat{T}$  is a constant and thus has zero variance.

As a result, if  $x$  is approximately proportional to  $y$  we may expect considerable precision in  $\hat{T}$  assuming our assumption about the  $p'_1$  is valid.

Note, however, that  $\hat{T}$  is not in general, unbiased. It is unbiased if  $\alpha = 1$ . In the special case  $k = N$ ,  $\alpha = 1$  and  $\hat{T}$  is again the Horvitz - Thompson estimator, which can be shown to be unbiased [14].

Although  $\hat{T}$  is not a combination of two separate estimators: one design-based and the other model-based, we shall still describe it as 'composite' being partly a design-based and partly a model-based (through the assumption concerning exposure probabilities).

**5. Approximate Mean and Variance of  $\hat{T}$**

Since  $X_k$  is a random variable, so is  $\alpha$ . Hence the estimator  $\hat{T}$  is a ratio of two random variables. As a result, to obtain the expectation and variance of  $\hat{T}$  we resort to approximation. Put

$$\hat{T} = X \frac{y^*}{x_k} = X z (Y^*, X_k)$$

where  $Y^* = \sum_i^n y_i / m_i$ . Using the inclusion indicator  $t_i$ , it can be readily established that:

$$E \left( \sum_i^n y_i / m_i \right) = \sum_i^N p'_i y_i \sim \frac{k}{N} T \quad \dots (5.1)$$

and that

$$V ( t_i ) = \pi_i ( k ) ( 1 - \pi_i ( k ) )$$

$$cov ( t_i , t_j ) = \pi_{ij} ( k ) - \pi_i ( k ) \pi_j ( k )$$

$$i \neq j$$

so that

$$V \left( \sum_i^n y_i / m_i \right) = V \left( \sum_i^N t_i y_i / m_i \right) = \sum_i^n \pi_i ( k ) ( 1 - \pi_i ( k ) ) \frac{y_i^2}{m_i^2}$$

$$+ \sum_{i \neq j}^N \frac{y_i}{m_i} \frac{y_j}{m_j} ( \pi_{ij} ( k ) - \pi_i ( k ) \pi_j ( k ) ) \quad \dots (5.2)$$

<sup>4</sup> Furthermore, denote by  $S_{ik}$  the  $i$  th ( $i = 1, \dots, c$ ) group of size  $k$  and by  $X_{ik}$  its total. Also, define the indicator  $a_i$  such that it takes the value 1 if  $S_{ik}$  is realized but 0 otherwise. Then from (3.10), and noting that one  $S_{ik}$  can occur at a time, we have for  $i = 1, \dots, c$  and  $j \neq i$ :



$$E ( a_i ) = \frac{1}{c} \quad , V ( a_i ) = \frac{1}{c} - \frac{1}{c^2} \quad , cov ( a_i , a_j ) = \frac{1}{c^2}$$

It follows that

$$E ( X_k ) = E \left( \sum_i^c a_i X_{ik} \right) = \frac{1}{c} \sum_i^c X_{ik}$$

And because each  $x_i$  appears  $\binom{N-1}{k-1}$  times in the total  $\sum_1^c X_{ik}$  we have

$$E ( X_k ) = \frac{k}{N} X \quad \dots (5.3)$$

It can also be verified that:

$$V ( X_k ) = \frac{1}{c} \left[ \sum_i^c X_{ik}^2 - \frac{1}{c} \left( \sum_i^c X_{ik} \right)^2 \right] = S^2 \quad \dots (5.4)$$

and

$$Cov \left( \sum_i^n y_i / m_i , X_k \right) \sim \frac{1}{c} \sum_j^N y_j \bar{X}_k^j - \left( \frac{k}{N} \right)^2 XT \quad \dots (5.5)$$

where  $\bar{X}_k^j$  is the sum of the sums of all  $X_{ik}$  for all groups  $S_{ik}$  in which unit  $j$  occurred.

**Approximate Mean.**

It is well known (e.g. Lindley [15] p. 135) that if  $z = (Y^*, X_k)$  is a function of  $Y^*$  and  $X_k$ , and if  $E(Y^*)$  and  $E(X_k)$  are the means of  $Y^*$  and  $X_k$  respectively, and  $V(Y^*)$  and  $V(X_k)$  their respective variances, then for sufficiently ,small  $\sqrt{V(Y^*)}$  and  $\sqrt{V(X_k)}$  and well-behaved  $z$ :

$$E ( z ) = z ( E ( Y^* ) , E ( X_k ) ) + \frac{1}{2} V ( Y^* ) \frac{\partial^2 z}{\partial Y^{*2}} +$$

$$Cov ( Y^* , X_k ) \frac{\partial^2 z}{\partial Y^* \partial X_k} + \frac{1}{2} V ( X_k ) \frac{\partial^2 z}{\partial X_k^2} \dots \dots (5.6)$$

$$V ( z ) = V ( Y^* ) \left( \frac{\partial z}{\partial Y^*} \right)^2 + 2 Cov ( Y^* , X_k ) \left( \frac{\partial z}{\partial X_k} \frac{\partial z}{\partial Y^*} \right) + V ( X_k ) \left( \frac{\partial z}{\partial X_k} \right)^2 \dots (5.7)$$

where all the partial differentials are evaluated at  $X_k = E(X_k)$  and  $Y^* = E(Y^*)$

But:

$$z(E(Y^*), E(X_k)) \sim \frac{T}{X}, \quad \frac{\partial^2 z}{\partial Y^{*2}} = 0, \quad \frac{1}{2} V(X_k) \frac{\partial^2 z}{\partial X_k^2} \sim \frac{N^2 S^2 T}{k^2 X^3}$$

and

$$\text{Cov}(Y^*, X_k) \frac{\partial^2 z}{\partial Y^* \partial X_k} \sim -\frac{N^2}{k^2 X^2 C} \sum_j y_j \bar{X}_k^j + \frac{T}{X}$$

and from (5.6)

$$E(z) = \frac{T}{X} - \left(\frac{N}{k}\right)^2 \frac{1}{X^2 C} \sum_j y_j \bar{X}_k^j + \frac{T}{X} + \left(\frac{N}{k}\right)^2 \frac{S^2 T}{X^3}$$

hence,

$$E(\hat{T}) = X E(z) = T + \left( \frac{N^2}{k^2 X^2} \left[ S^2 T - \frac{X}{C} \sum_j y_i \bar{X}_k^j \right] + T \right) \dots (5.8)$$

Since  $\bar{X}_k^j$  is the sum of the sums of  $\binom{N-1}{k-1}$  groups each of size  $k$ , it follows that

$$\frac{N^2}{k^2 X C} \sum_j y_i \bar{X}_k^j = \frac{N}{X} \sum_j y_i \bar{\bar{X}}_k^j$$

where  $\bar{\bar{X}}_k^j$  is the mean per unit for the units contained in all subsets of size  $k$  containing  $j$ . The mean  $\bar{\bar{X}}_k^j$  should not differ much from the overall mean per unit  $\bar{X}$  and we can thus put

$$\frac{N^2}{k^2 X C} \sum_j y_i \bar{X}_k^j \approx T$$

so that (5.8) simplifies to

$$E(\hat{T}) \approx T \left( 1 + \frac{S^2}{k^2 X^2} \right)$$

This result shows that, subject to the validity of the exposure model, and the order of the approximation used, the bias in  $\hat{T}$  approaches zero as  $S^2 \rightarrow 0$ . Of course, this bias is zero if  $k = N$  for then  $S^2 = 0$ .

**Approximate Variance**

By an argument similar to that used in arriving at (5.8) and with reference to (5.7) it can be shown that

$$\begin{aligned}
 V(\hat{T}) \approx & \frac{N^2}{k^2} \left[ \sum_i^N \pi_i(k) (1 - \pi_i(k)) \frac{y_i^2}{m_i^2} + \sum_i^N \sum_{*j}^N \frac{y_i}{m_i} \frac{y_j}{m_j} (\pi_{ij}(k) - \pi_i(k) \pi_j(k)) \right] \\
 & + \frac{N^2 T^2 S^2}{k^2 X^2} - \frac{2N^2 T}{k^2 X} \left\{ \frac{1}{C} \sum_j^N y_j \bar{X}_k^j - \frac{k^2}{N^2} XT \right\} \quad \dots (5.9)
 \end{aligned}$$

the last term in (5.9) can be written as

$$-2 \frac{N^2 T}{k^2 X} \left\{ \frac{1}{C} \sum_j^N y_j \bar{X}_k^j - \frac{k^2}{N^2} XT \right\} = \frac{NT}{X} \sum_j^N y_j \bar{\bar{X}}_k^j - T^2$$

Again if  $\bar{\bar{X}}_k^j = \bar{X}$  this term vanishes, and since  $\bar{\bar{X}}_k^j$  is expected to be close to  $\bar{X}$  we may eliminate this term from (5.9) which then takes the relatively simpler form

$$\begin{aligned}
 V(\hat{T}) \approx & \frac{N^2}{k^2} \left[ \sum_i^N \pi_i(k) (1 - \pi_i(k)) \frac{y_i^2}{m_i^2} \right. \\
 & \left. + \sum_i^N \sum_{*j}^N \frac{y_i}{m_i} \frac{y_j}{m_j} (\pi_{ij}(k) - \pi_i(k) \pi_j(k)) \right] \\
 & + \frac{N^2 T^2 S^2}{k^2 X^2} = V^*(\hat{T}) \quad \text{say.}
 \end{aligned}$$

Note that if  $k = N$ , then  $\pi_i(k) = m_i$  and  $S^2 = 0$  so that  $V^*(\hat{T})$  becomes the variance of the Horvitz - Thompson estimator  $\hat{T}_{HT}$ .

We may think of the quantity within the square brackets as giving the variance of  $\hat{T}$  when the sampled population is the target population. When the actual population is a subset of the target population, a component representing the between actual populations variability must be included in the expression of variance. This is supplied by the last term in the above expression.

### 6. Estimation of $V^*(\hat{T})$

To estimate the approximate variance  $V^*(\hat{T})$  we first estimate  $S^2$ . Suppose  $C'$  ( $C' < C$ ) subsets of  $U$ , of size  $k$  each are exposed independently. For ease of reference, let these be  $S_{1k}, S_{2k}, \dots, S_{c'k}$ . Then using the indicator variable of section (5) we get

$$E \left( \sum_i^{c'} X_{ik}^2 \right) = \sum_i^c X_{ik}^2 E(a_i) = \frac{1}{C} \sum_i^c X_{ik}^2$$

So an unbiased estimator of  $\sum_i^c X_{ik}^2$  is  $C \sum_i^{c'} X_{ik}$ .

On the other hand, since each unit appears in  $\binom{N-1}{k-1}$  of the  $X_{ik}$ 's each unit contributes its value that number of times in the sum  $\sum_i^c X_{ik}$ . Therefore

$$\sum_i^c X_{ik} = \binom{N-1}{k-1} X$$

and  $S^2$  can be written as

$$S^2 = \frac{1}{C} \left\{ \sum_i^c X_{ik}^2 - \frac{1}{C} \binom{N-1}{k-1}^2 X^2 \right\}$$

Because  $X$  is assumed known, an unbiased estimator of  $S^2$  is

$$\begin{aligned} \hat{S}^2 &= \frac{1}{C} \left\{ C \sum_i^{c'} X_{ik}^2 - \frac{1}{C} \binom{N-1}{k-1}^2 X^2 \right\} \\ &= \sum_i^{c'} X_{ik}^2 - \left( \frac{k}{N} X \right)^2 \end{aligned}$$

Similarly, using the indicator  $t_i$  we note that

$$E \left( \sum_i^n y_i \right)^2 = \sum_i^N y_i^2 \pi_i(k) + \sum_i^N \sum_{j \neq i}^N y_i y_j \pi_{ij}(k)$$

Hence

$$\hat{y} = \sum_i^n \frac{y_i^2}{\pi_i(k)} + \sum_i^n \sum_{j \neq i}^n \frac{y_i y_j}{\pi_{ij}(k)}$$

is an unbiased estimator of  $T^2$ . Assuming  $\hat{y}$  and  $\hat{S}^2$  independent, and employing t, we finally arrive at

$$v^*(\hat{T}) = \frac{N^2}{k^2} \left[ \sum_i^n (1 - \pi_i(k)) \frac{y_i^2}{m_i^2} + \sum_i^n \sum_{j \neq i}^n \frac{y_i y_j}{m_j} (\pi_{ij}(k) - \pi_i(k) \pi_j(k)) \right] + \frac{N^2 y \hat{S}^2}{k^2 X^2}$$

which is an unbiased estimator of  $V^*(\hat{T})$ .

### 7. Other Versions of $\hat{T}$

Other estimators for  $T$  that are versions of  $\hat{T}$  may also be suggested. The first version is obtained by substituting  $\frac{nx_i}{X_k}$  for  $m_i$  in (4.7) to get the estimator.

$$\hat{T}' = \frac{X}{n} \sum_{i=1}^n \frac{y_i}{X_i} \quad \dots (7.1)$$

The advantage of this estimator is that it enables us to make use of standard results in the theory of ratio estimators. Thus the expectation of  $\hat{T}'$  (within and over the  $S_k$ 's) will take the form:

$$E(\hat{T}') = X\hat{R}$$

where  $\hat{R}$  is the expected value of a ratio in simple random sample of size  $k$  from the target population ( $U$ ). The variance of  $\hat{T}'$  may be obtained by using

$$V_k(\hat{T}') = E_k \frac{X^2}{X_k^2} V_k \left( \hat{T}'_{(k)} \right) + V_k \frac{X}{X_k} T_k \quad (7.2)$$

where  $E_k$  &  $V_k$  means taking expectation and variance over all groups of size  $k$  respectively, and

$$\hat{T}'_{(k)} = \frac{X_k}{n} \sum_{i=1}^n \frac{y_i}{X_i}$$

$$T_k = \sum_{i=1}^k y_i$$

A second estimator, also a version of  $\hat{T}$ , is obtained by assuming Lahiri-Midzuna [12,13] scheme in which the inclusion probabilities are proportional to  $\sum_{i=1}^n x_i$ . If

in (4.7) we substitute  $\frac{\sum_{i=1}^n X_i}{X_k}$  for  $m_i$  we get the estimator.

$$\hat{T}'' = \frac{\sum_{i=1}^n y_i}{\sum_{i=1}^n X_i} X \quad (7.3)$$

The expected value of  $\hat{T}''$  is approximately  $X\bar{R}$ .

A third version of  $\hat{T}$  is obtained by simply substituting  $k/N$  for  $\alpha$  and  $nx_i/X_k$  for  $m_i$  in (4.7) to get

$$\hat{T}''' = \frac{N}{k} \sum_{i=1}^n y_i / m_i$$

which, though slightly inferior, yet unbiased.

The main problem with the estimators  $\hat{T}'$ ,  $\hat{T}''$  and  $\hat{T}'''$  is that the explicit forms of their variance have not yet been derived. It is therefore difficult to assess their relative precision. The three estimators are suggested to me by a referee to whom I am grateful.

### 8. Concluding Remarks

In the preceding discussion, an attempt is made to generalize the Horvitz - Thompson estimator,  $\hat{T}_{HT}$ , so as to incorporate the situation in which units are exposed to sampling with preassigned probabilities. The proposed estimator  $\hat{T}$ , seems to provide small bias and high precision, assuming  $x$  and  $y$  proportional, if  $S^2$  is small *i.e* if there is little variability between the exposed (actual) populations  $S_{ik}$ . It is however important to remember that, apart from the approximation used, the extend to which we can rely on results about bias and precision of  $\hat{T}$  depends on the validity of the assumed model.

It is informative to view  $\hat{T}$  from a different angle. The estimator  $\hat{T}_{HT} = \sum_i^n y_i / m_i$ , assuming (4.4), estimates the total of  $S_k$  and not  $U$ , and hence it underestimates  $T$ . By dividing it by  $\alpha$ , the ratio of the total of  $x$  in  $S_k$  to that in  $U$ , underestimation is reduced. The factor  $\frac{1}{\alpha}$  in  $\hat{T}$  thus, in a sense, works as an inflator that helps compensate for the underestimation incurred when using  $\hat{T}_{HT}$  alone.

A practical implication of the preceding discussion is that if the actual population differs from the target population, and if exposure probabilities are equal, then  $\hat{T}_{HT}$  will no longer be unbiased with small variance. This is so even if (4.4) is satisfied and  $x$  and  $y$  proportional. The extend of the bias and precision in  $\hat{T}$  depends on the relative sizes of the actual and target populations as well as on inter-actual population variability.

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## مقدار مركب للمجموع في مجتمع محدود

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ملخص البحث . نتناول الحالة التي يكون فيها المجتمع الذي تجرى معاينته جزء من مجتمع محدود أكبر تعرض لعملية المعاينة وفق توزيع احتمالي معين . احتمالات التعرض للمعاينة تتحدد بشكل مستقل عن طريقة المعاينة المستخدمة . تم اقتراح مقدار مركب لمجموع المجتمع مع صيغة تقريبية لتوقعه وتباينه . كذلك تم اقتراح مقدر غير متحيز للتباين .

